



The Football Field Generator Program

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Painting the Brookwood High School Football Field

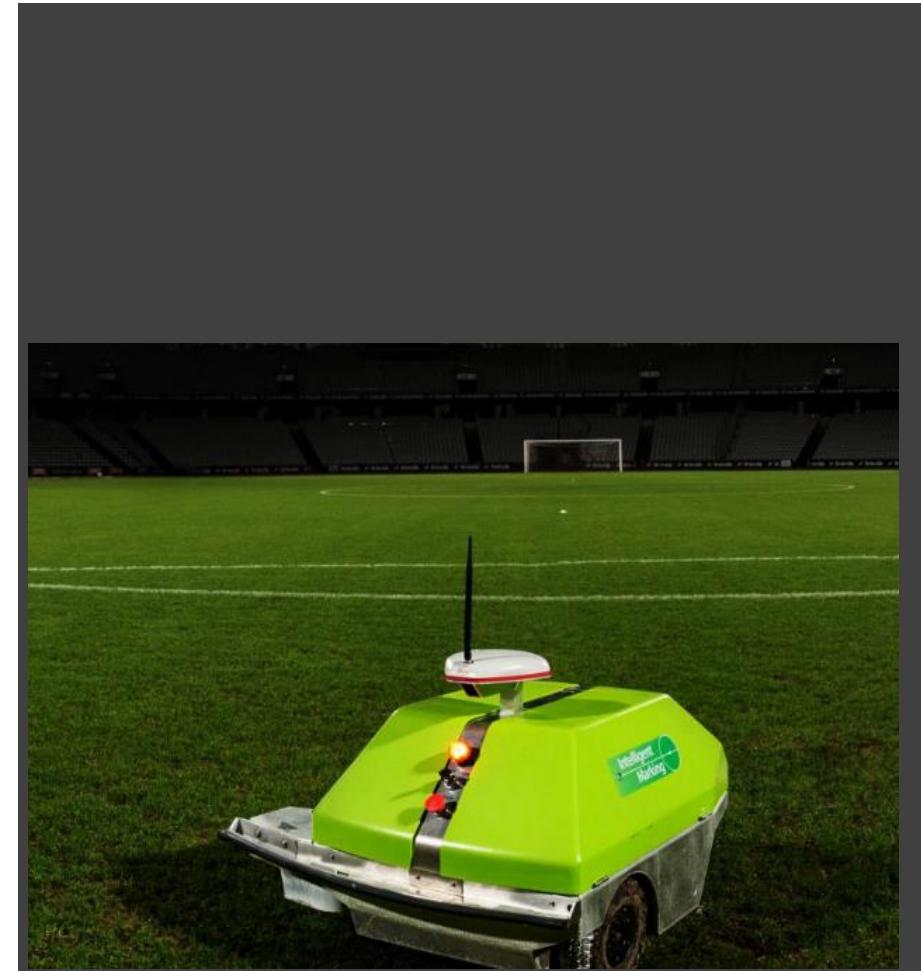


Cost to paint Field

Manual Method

- Total Labor Hours = 20 (4 man)
- Paint Consumption = 25 gallons
- Labor Cost = \$330 per field marking (16.50 hr./pay)
- Paint Cost = \$250 per field
- Cost Per Season = \$4,640
- Contracted Cost = \$500/game plus paint





Intelligent One (ION)

Intelligent One (ION)



Intelligent One

- Total Operation Hours = 3
- Paint Consumption = 10 gallons
- Labor Hours Savings = \$2,640 annually
- Paint Cost Savings = \$1,200 annually

<https://turftank.com/intelligentone/>

Intelligent One

- Requested changes to program to outline endzone letters
 - Manually, requires a team of 5 over 8 hours to outline the endzones prior to the first game
 - Letters have to be replotted near end of season which requires the same level of effort
- Would require significant cost increase to intelligent one program and would take over a year to program according to turftank

WHY?

Project Overview

- Utilize Python to develop the longitude and latitude points for all lines of a football field
 - Provide a table of start and stop points to avoid having to survey the field each year
 - Provide a table of start and stop points to feed into the “football Roomba” to understand the concepts behind the intelligent One
 - Graphic proof of calculations to demonstrate the calculations and layout

Project Overview

Utilized the formula that gave the longitude and latitude of the second point using the following formula where θ = bearing, A = radius of the earth in feet and d = distance travelled

$$\text{latitude of second point} = \text{la2} = \text{asin}(\sin \text{la1} * \cos \text{Ad} + \cos \text{la1} * \sin \text{Ad} * \cos \theta)$$

$$\text{longitude of second point} = \text{lo2} = \text{lo1} + \text{atan2}(\sin \theta * \sin \text{Ad} * \cos \text{la1}, \cos \text{Ad} - \sin \text{la1} * \sin \text{la2})$$

Project Parameters

- Imported Modules
 - Math for Trig functions and PI
 - Turtle for Drawing
- $A = 20902230.971129$ feet
- Length of field = 360 feet
- Width of field = 180 feet
- Length of hashmark = 2 feet

Project Steps

- Input the starting parameters of latitude, longitude and bearing and error check
 - Note: formula breaks down at north and south pole. Therefore latitude was limited to +/-75 degrees
- Calculate the Endzone corner points
 - EZ1 = 80 feet from starting point at the bearing + 90 degrees
 - EZ2 = 80 feet from starting point at the bearing – 90 degrees
 - EZ3 = 360 feet from EZ1 at the bearing
 - EZ4 = 360 feet from EZ2 at the bearing

Project Steps (Continued)

- Yardlines are at 30 feet, 45 feet and continue every 15 feet until 330 feet from starting end line
 - Yardline starting point = EZ1 + the distance at the bearing angle
 - Yardline ending point = EZ2 + the distance at the bearing angle
- Hashmarks are every yard between the yardlines but aren't inside the endzone (33 , 36, 39, 42, 48, 51 feet etc)
 - Hashmarks near the sidelines are .5 feet inside the sidelines
 - Starting point for hash marks are
 - Sideline 1 starting point = starting point + 79.5 feet at the bearing angle + 90 degrees
 - Sideline 1 ending point = starting point + 77.5 feet at the bearing angle + 90 degrees

Proof of Concept Plotting

- Used turtle and converted longitude and latitude to x,y coordinates for plotting
 - Set midpoint of field to be (0,0) on turtle screen
 - Calculated change in latitude and longitude between two points to determine change in feet / change in degree to convert to x,y
 - Used two equation two unknown algebraic logic to solve for x,y coordinates
 - Each pixel represents .5 feet in turtle
- Two equation logic failed at bearings 0, 45, 90, 135, 180, 235, 270, 315, 360
 - Used separate logic to address those conditions

Drawing Steps

- Changed background to yellow
- Added title to drawing window
- Drew a Black border around field
- Changed field color to green
- Drew white sidelines on top of black border
- Drew yardmarkers
- Drew hashmarks
- Added bearing arrow
- Added name
- Added pause to wait on user click

